CS/ECE/EEE/INSTR F241 – MICROPROCESSOR PROGRAMMING & INTERFACING

MODULE 3: ADDRESSING MODES OF 80X86

QUESTIONS

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- Q1. If the register field "REG" of an instruction contains 101 and "w"=0, What is the register selected assuming that instruction is a 16-bit mode instruction?
- **Q2.** The instruction MOV DS, 2300h gives an error. Why?
- Q3. For the following instructions determine the addressing mode and the Machine code

Assume instructions are in 16-bit mode of operation

- MOV ECX ,CC001267H
- MOV AX,SI
- MOV [SI],CL
- MOV AX,CS:[DI+1000h]
- MOV CL,[EDX+EDI]
- MOV EAX,4020[BX+DI]
- MOV BX,[EBX+2*ECX]
- MOV BL,SS:[ECX]
- MOV CX,CX
- Q4. Suppose that $CS = 1000_H$, $ES = 8000_H$, $DS = A000_H$, $SS = 7000_H$, $ESI = 0000 0200_H$, $EDI = 0000 0410_H$, $EBP = 0000 2300_H$, $EBX = 0000 0200_H$ $EAX = 0000 0400_H$, $ECX = 0000 0020_H$, $EDX = 0000 0008_H$ For the instructions given below determine the machine code, address & addressing mode. Processor is working 32-bit mode
 - MOV [SI+100_H],EAX
 - MOV [EAX+2*EBX],CL
 - MOV DH,CS:[EBX+4*EAX+1000_H]
 - MOV [BP+SI+2000_H],CX
- Q5. Suppose that in 8086 DS = 1300_{H} , BP = 0100_{H} , SS = 1000_{H} ,SI = 0250_{H} . Determine the address accessed by each of the following instructions
 - MOV AX,[BP+200H]
 - MOV AL,[BP+SI-200H]
 - MOV AL,[SI-0100H
- **Q6.** Determine the instruction from the opcode assume the processor is working in 16-bit mode.

All instructions are some form of MOV.

- 66 89 D8
- 89 46 10
- B1 45
- 67 8A 44 7D 02

- Q7. In an 80386 processor that is working in real mode and 16-bit mode: Suppose that CS =0000 $_{\rm H}$, ES = F000 $_{\rm H}$, DS=4000 $_{\rm H}$, SS = 2000 $_{\rm H}$, ESI= 0000 0100 $_{\rm H}$, EDI = 0000 0210 $_{\rm H}$, EBP = 0300 $_{\rm H}$, EBX=0000 4000 $_{\rm H}$, EAX=0000 0200 $_{\rm H}$, ECX = 0000 0010 $_{\rm H}$, EDX = 0000 0004 $_{\rm H}$ For the instructions given below determine the following: Memory Address, Addressing Mode and Machine Code [Give Values only in Hex and treat instructions as separate individual instructions]
 - MOV ES: [1000_H], AH
 - MOV EAX, SS:[EBX+8]
 - MOV CH,[SI+BP+100_H]
 - MOV EAX, [SI+BX]
 - MOV AL,[EBX+8*ECX+20_H]